
The FEniCS Project

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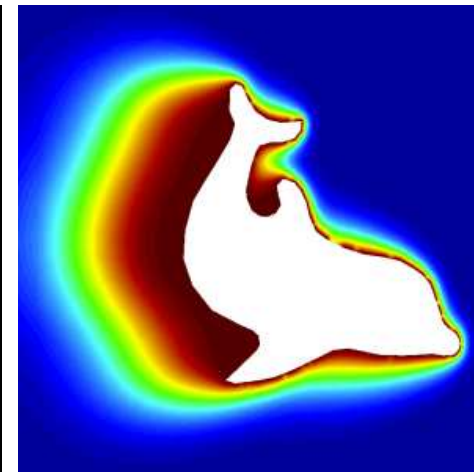
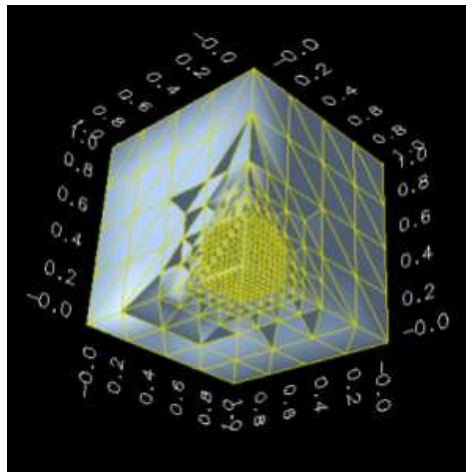
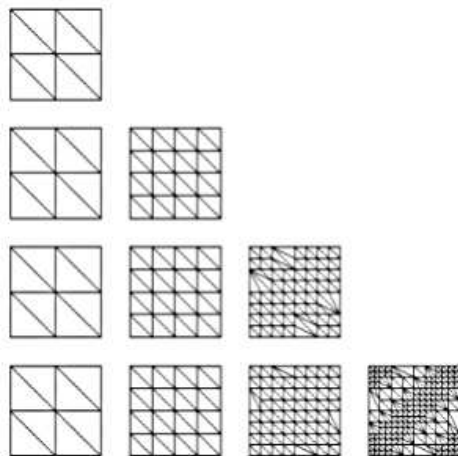
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<http://www.fenics.org/>

The **FEniCS** project

A free software project for the Automation of Computational Mathematical Modeling (ACMM), developed at

- The Toyota Technological Institute at Chicago
- The University of Chicago
- Chalmers University of Technology (Göteborg, Sweden)
- NADA, KTH (Stockholm, Sweden)
- Argonne National Laboratory (Chicago)



People

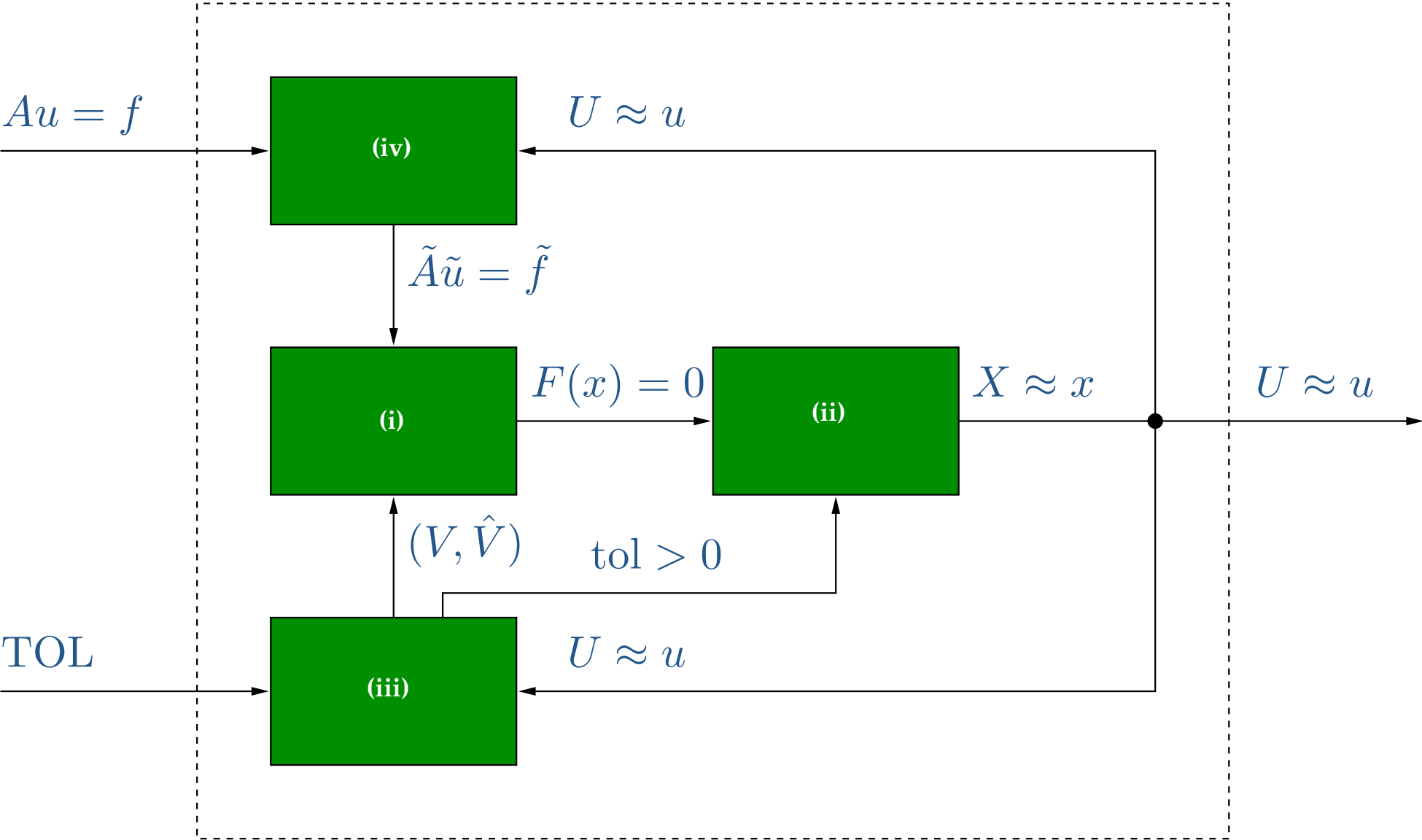
- Todd Dupont, University of Chicago
- Johan Hoffman, NADA
- Johan Jansson, Chalmers University of Technology
- Claes Johnson, Chalmers University of Technology
- Matthew Knepley, Argonne National Laboratory
- Robert C. Kirby, University of Chicago
- Mats G. Larson, Umeå University
- Anders Logg, Toyota Technological Institute at Chicago
- Ridgway Scott, University of Chicago
- F. Bengzon, N. Ericsson, G. Fofas, D. Heintz, R. Hemph, P. Ingelström, K. Kraft, A. Krusper, A. Mark, A. Nilsson, E. Svensson, J. Tilander, T. Svedberg, H. Svensson, W. Villanueva

Main goal: the Automation of CMM



- Input: Model $Au = f$ and tolerance $TOL > 0$
- Output: Solution $U \approx u$ satisfying $\|U - u\| \leq TOL$
- Produce a solution U satisfying a given accuracy requirement, using a minimal amount of work

The Automation of CMM

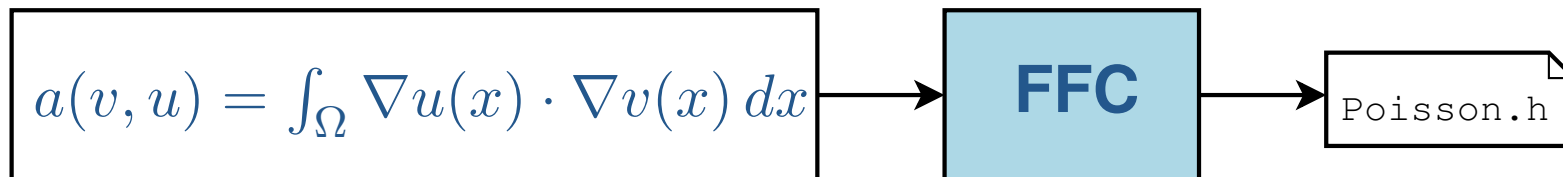


FEniCS components

- **DOLFIN**, the C++ interface of FEniCS
 - Hoffman, Jansson, Logg, et al.
- **FErari**, optimized form evaluation
 - Kirby, Knepley, Scott
- **FFC**, the FEniCS Form Compiler
 - Logg
- **FIAT**, automatic generation of finite elements
 - Kirby, Knepley
- **Ko**, simulation of mechanical systems
 - Jansson
- **Puffin**, light-weight version for Octave/MATLAB
 - Hoffman, Logg
- (PETSc)

FFC: the FEniCS Form Compiler

- Automates a key step in the implementation of finite element methods for partial differential equations
- Input: a variational form and a finite element
- Output: optimal C/C++ code

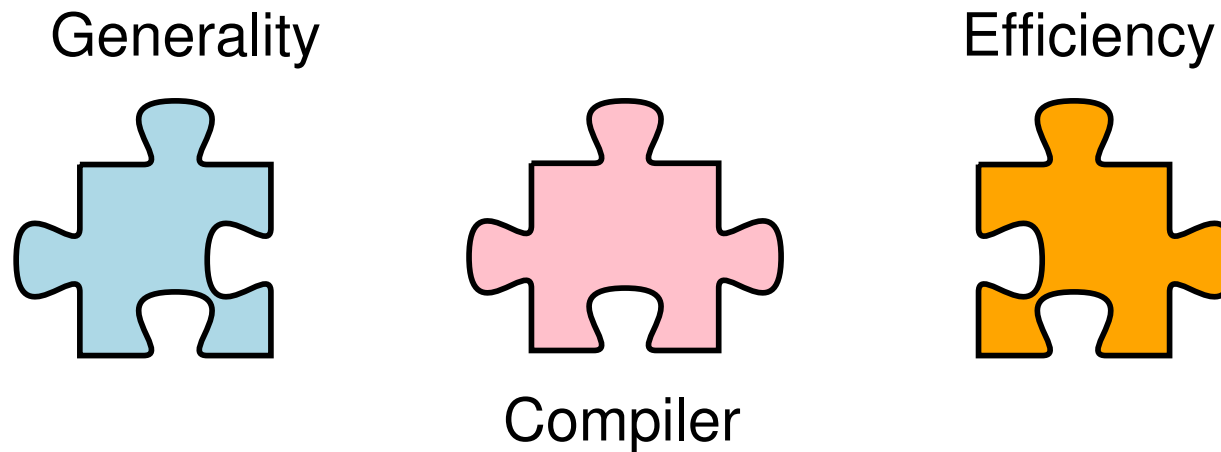


```
>> ffc [-l language] poisson.form
```

Design goals

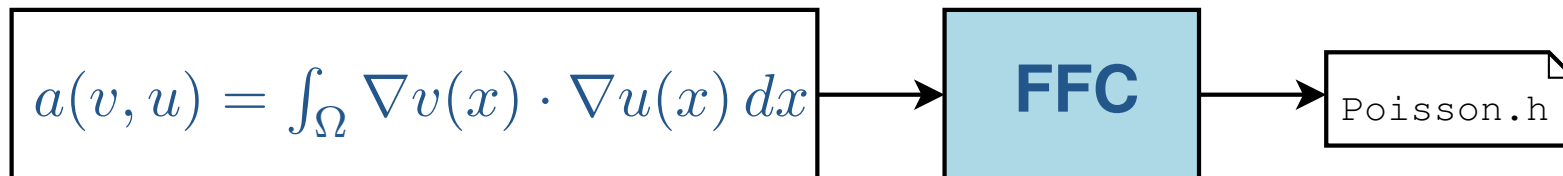
- Any form
- Any element
- Maximum efficiency

Possible to combine generality with efficiency by using a compiler approach:

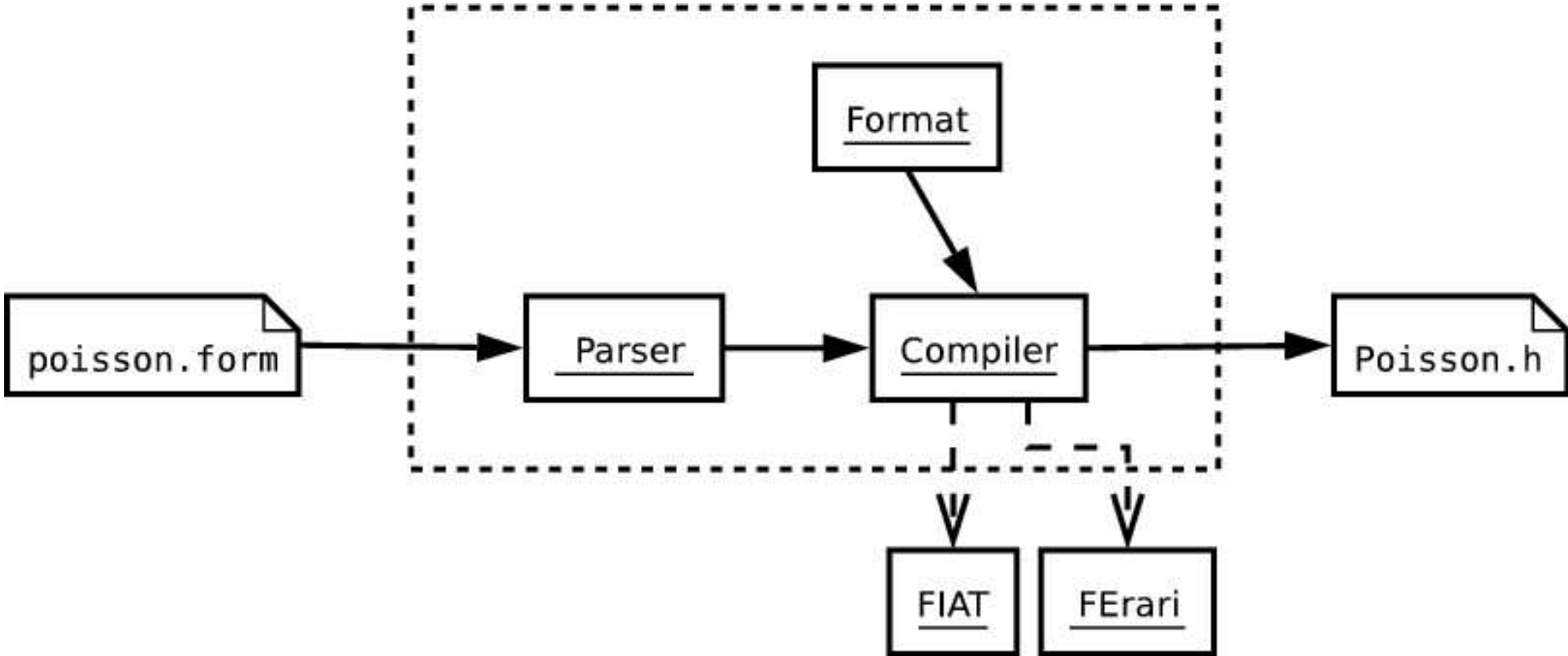


FFC

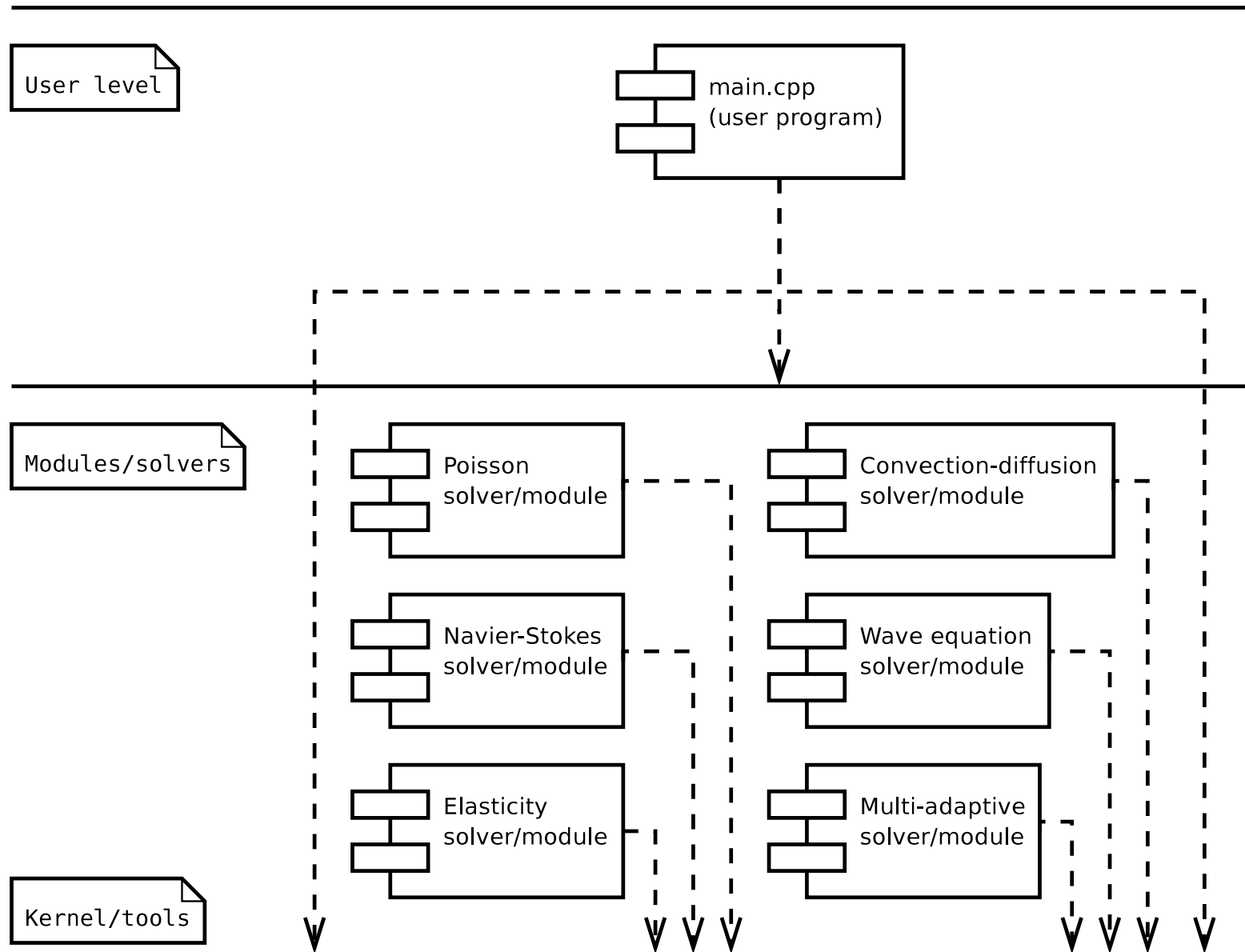
- Implemented in Python
- Access: Python module or command-line interface
- **FIAT** used as the finite element backend
- Optimization through **FErari**
- Supports multiple output languages (formats)
- Primary target: **DOLFIN/PETSc**



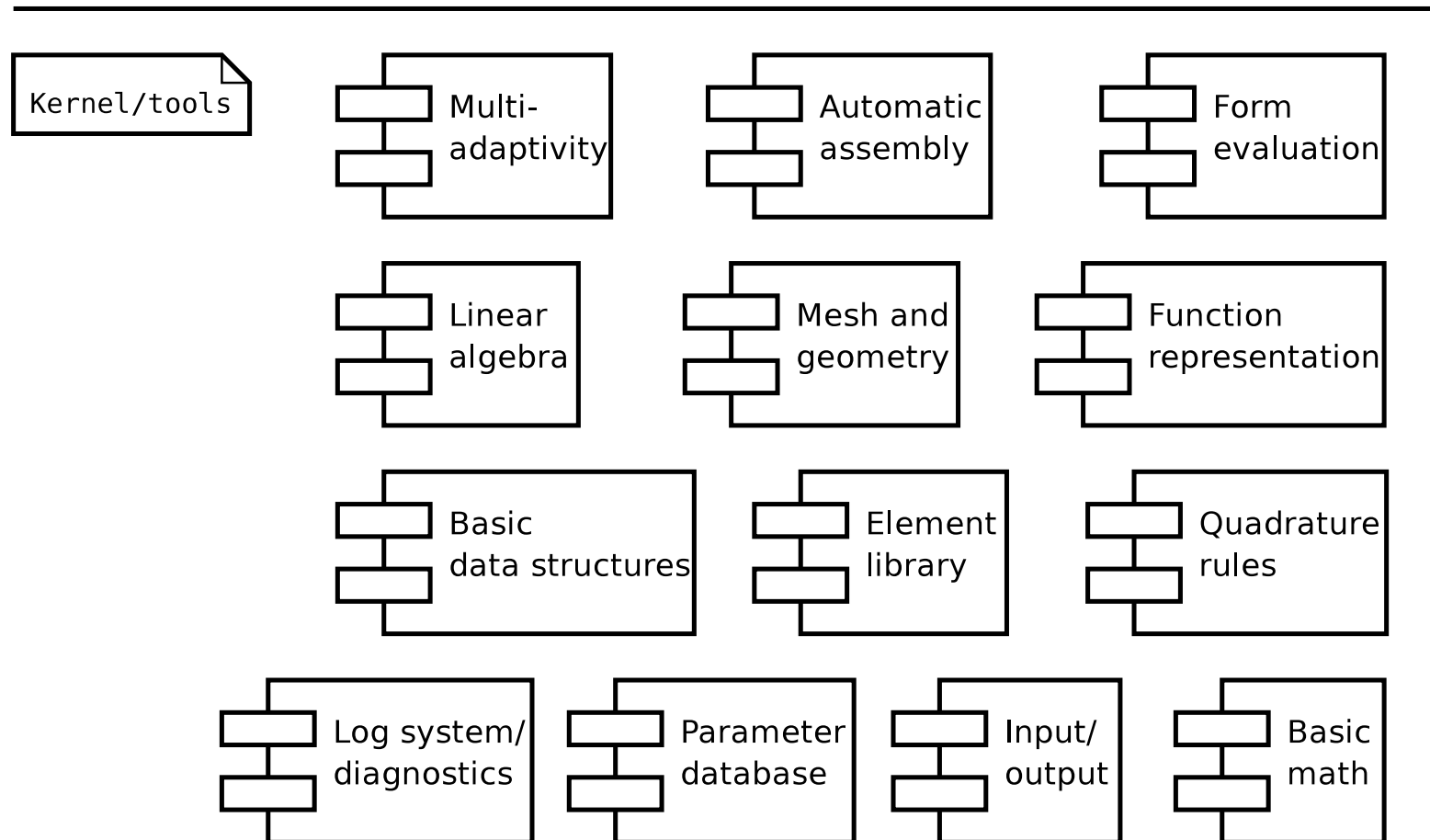
Components of FFC



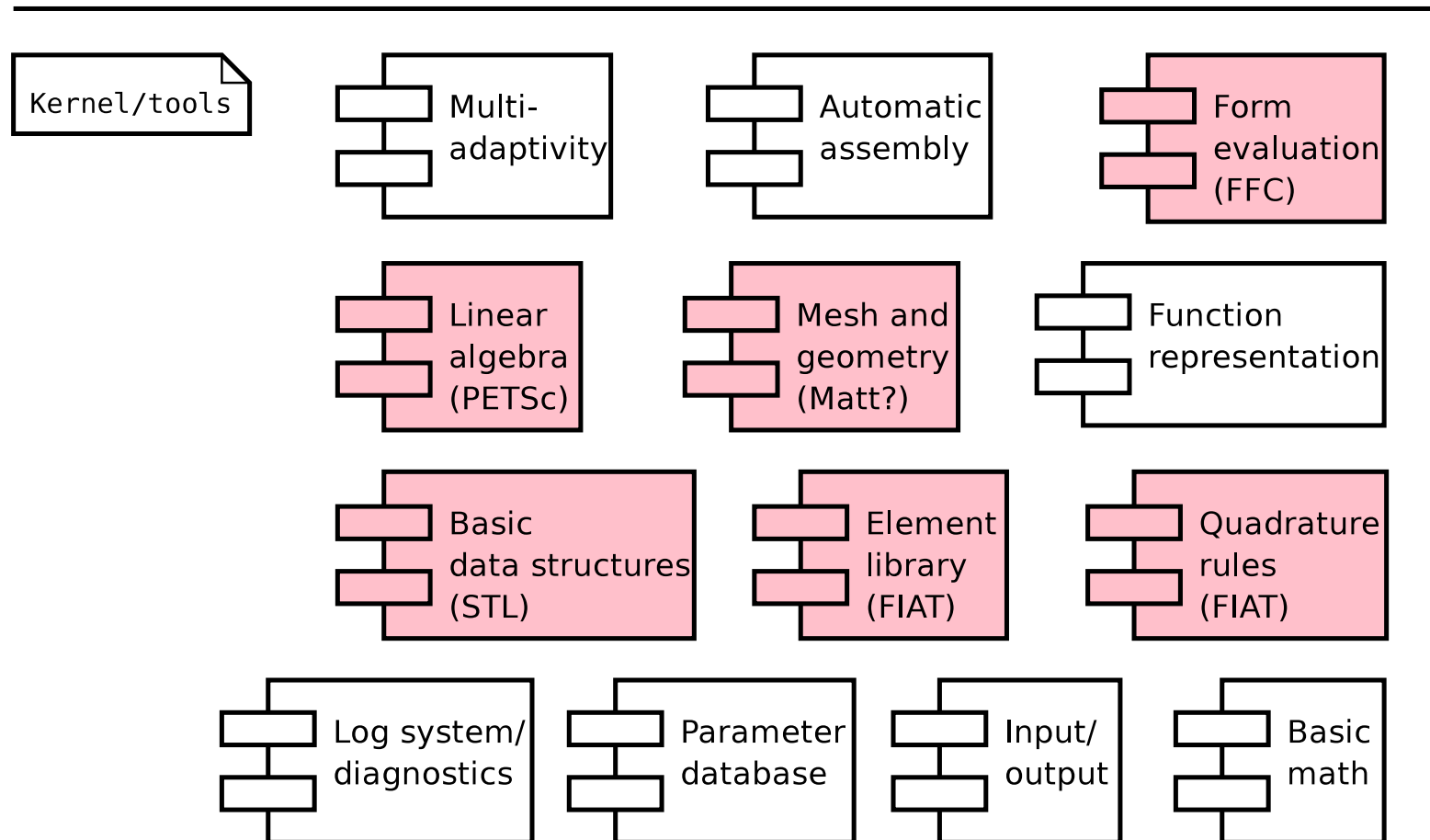
DOLFIN



DOLFIN

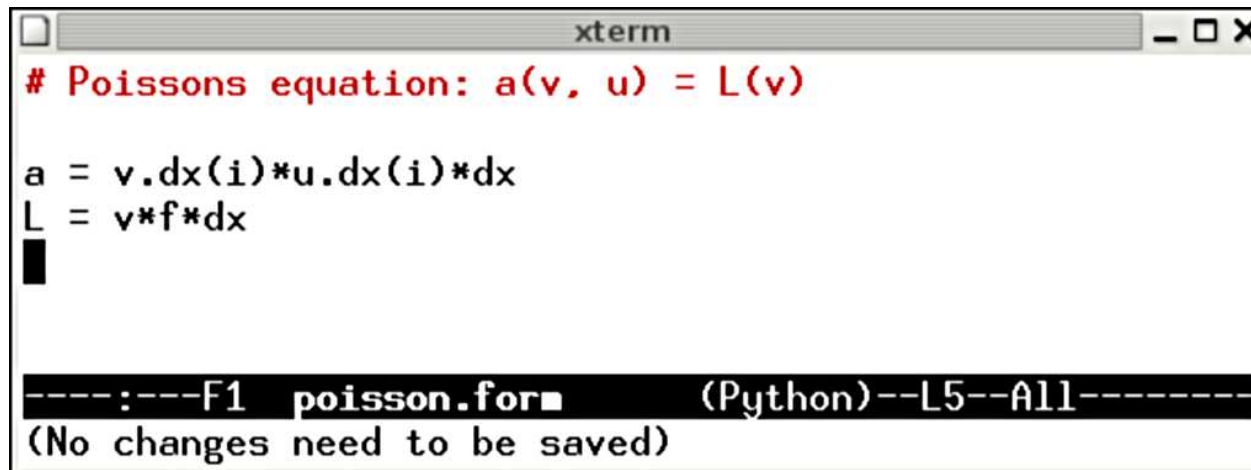


DOLFIN becomes an interface



Basic usage: compiling a form

1. Implement the form using your favorite text editor (emacs):



```
xterm
# Poissons equation: a(v, u) = L(v)

a = v.dx(i)*u.dx(i)*dx
L = v*f*dx
█

----:---F1 poisson.form (Python)--L5--A11-----
(No changes need to be saved)
```

2. Compile the form using **FFC**:

```
>> ffc poisson.form
```

This will generate C++ code (`Poisson.h`) for **DOLFIN**

Basic usage: solving the PDE

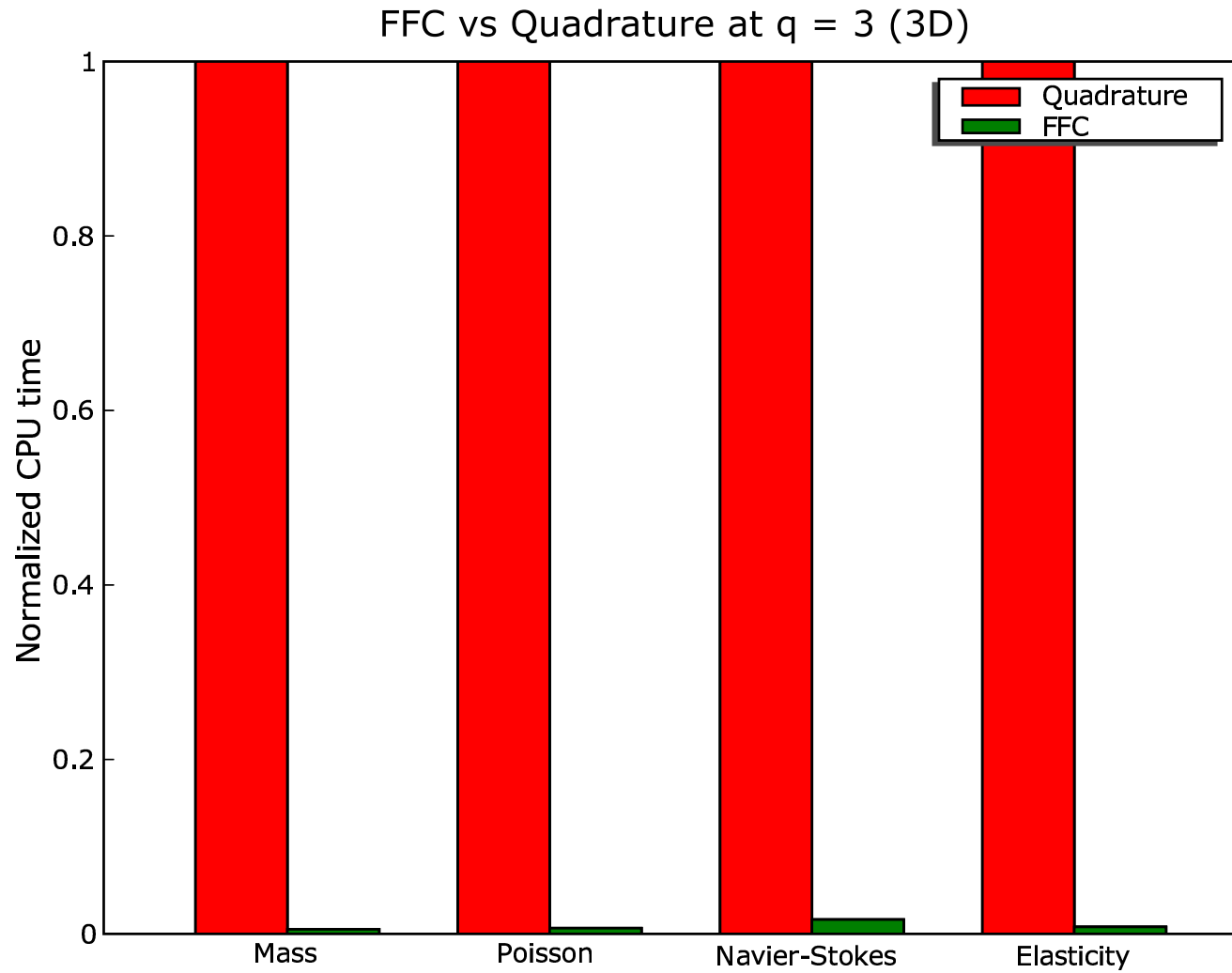
```
#include <dolfin.h>
#include "Poisson.h"
using namespace dolfin;
int main()
{
    Poisson::BilinearForm a;
    Poisson::LinearForm L(f);

    Matrix A;
    Vector x, b;
    FEM::assemble(a, L, A, b, mesh, bc);
    GMRES::solve(A, x, b);

    Function u(x, mesh, a.trial());
    File file("poisson.m");
    file << u;

    return 0;
}
```

Impressive speedups



Test case 1: the mass matrix

- Mathematical notation:

$$a(v, u) = \int_{\Omega} uv \, dx$$

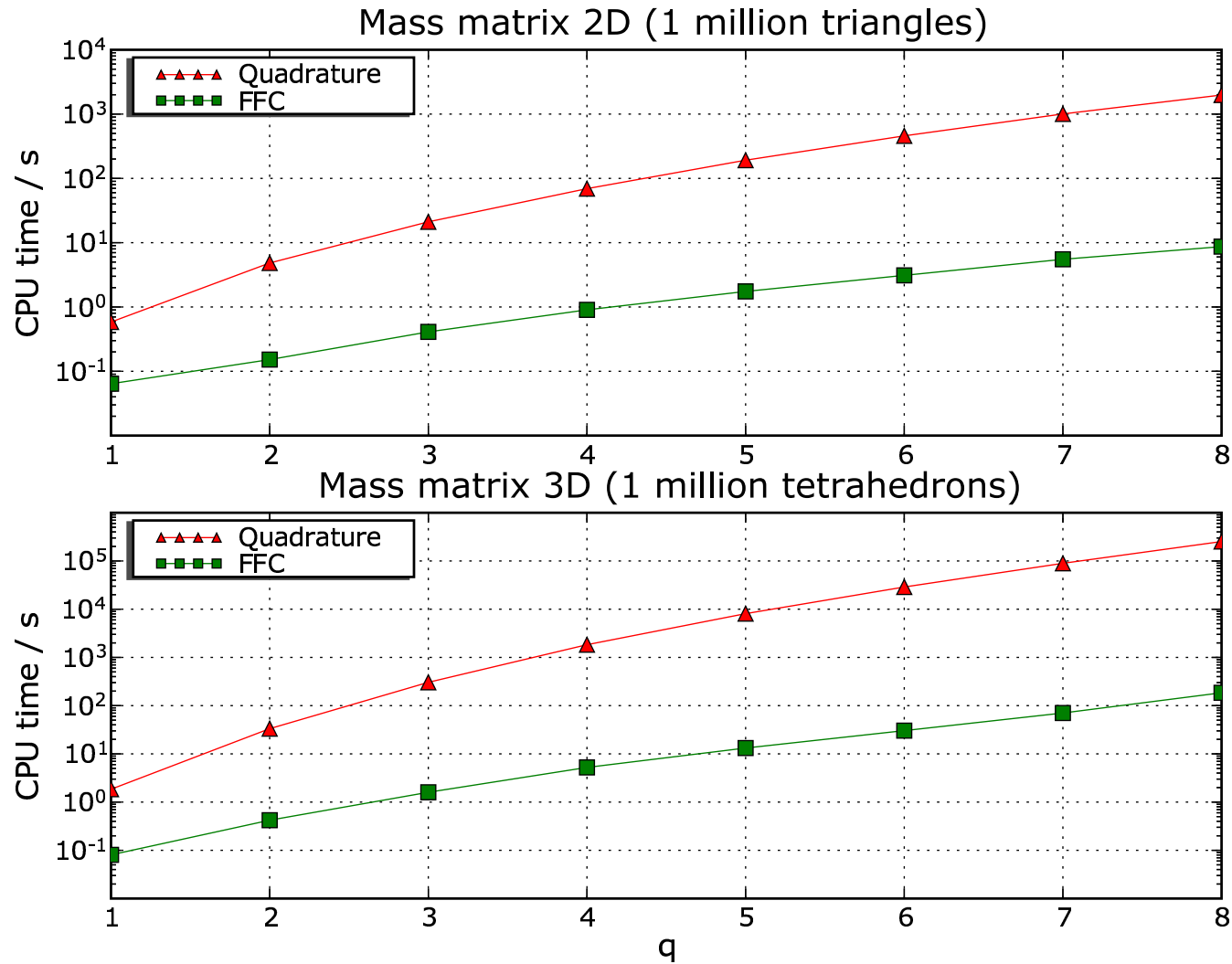
- FFC implementation:

```
v = BasisFunction(element)
```

```
u = BasisFunction(element)
```

```
a = u*v*dx
```

Results



Test case 2: Poisson

- Mathematical notation:

$$a(v, u) = \int_{\Omega} \nabla u \cdot \nabla v \, dx = \int_{\Omega} \sum_{i=1}^d \frac{\partial u}{\partial x_i} \frac{\partial v}{\partial x_i} \, dx$$

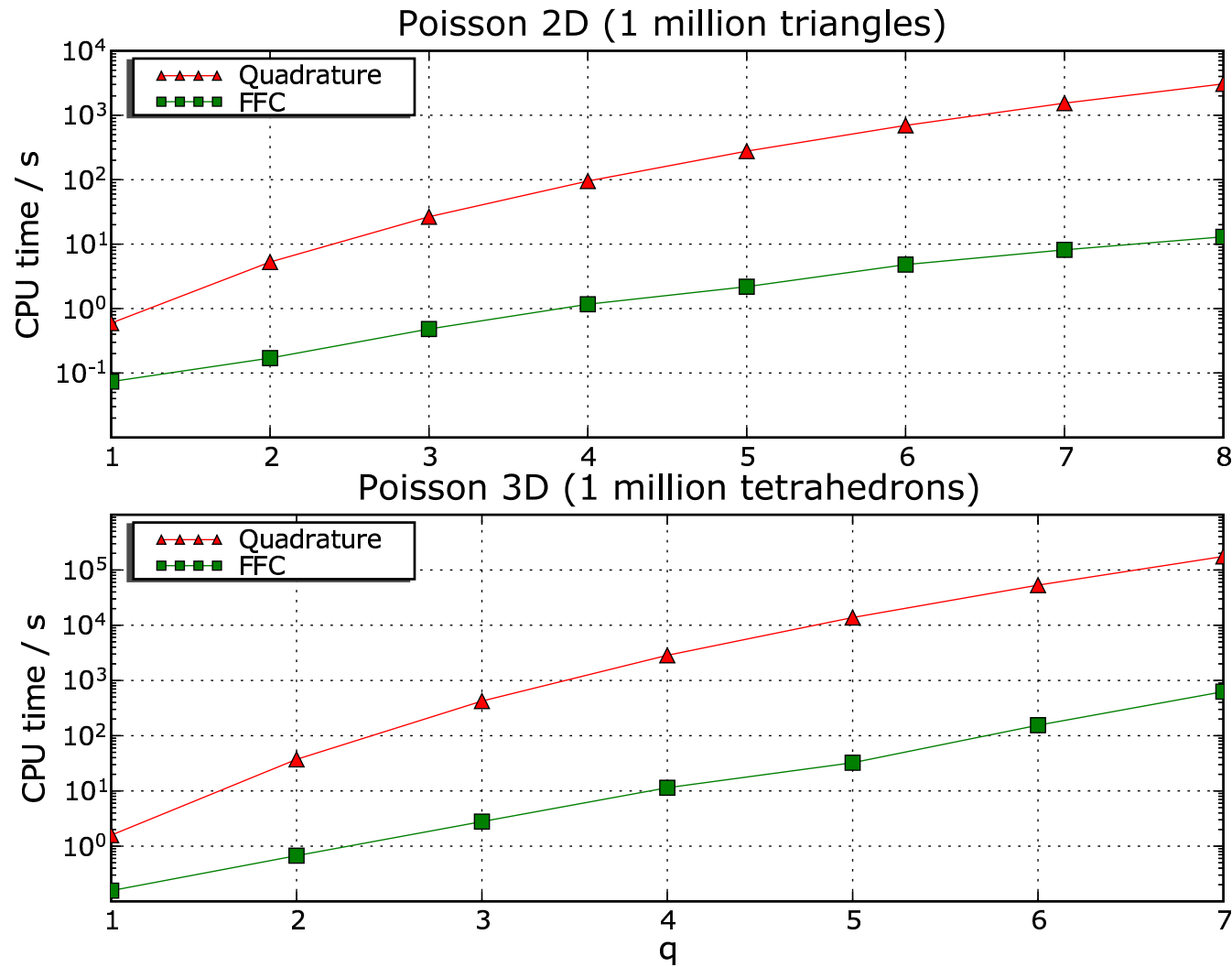
- FFC implementation:

```
v = BasisFunction(element)
```

```
u = BasisFunction(element)
```

```
a = u.dx(i) * v.dx(i) * dx
```

Results



Test case 3: Navier–Stokes

- Mathematical notation:

$$a(v, u) = \int_{\Omega} (w \cdot \nabla u) v \, dx = \int_{\Omega} \sum_{i=1}^d \sum_{j=1}^d w_j \frac{\partial u_i}{\partial x_j} v_i \, dx$$

- FFC implementation:

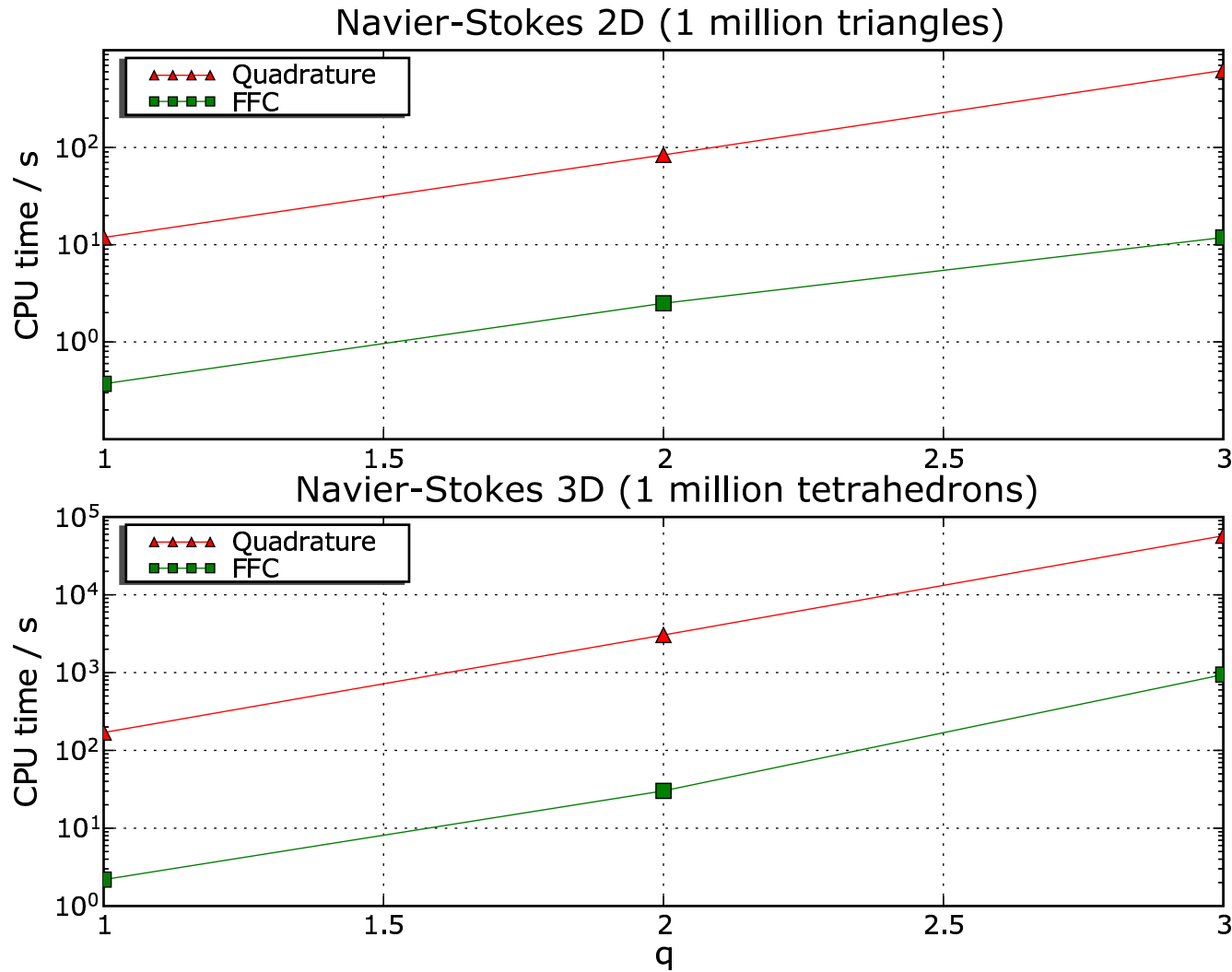
```
v = BasisFunction(element)
```

```
u = BasisFunction(element)
```

```
w = Function(element)
```

```
a = w[j]*u[i].dx(j)*v[i]*dx
```

Results



Test case 4: Linear elasticity

- Mathematical notation:

$$\begin{aligned} a(v, u) &= \int_{\Omega} \frac{1}{4} (\nabla u + (\nabla u)^{\top}) : (\nabla v + (\nabla v)^{\top}) dx \\ &= \int_{\Omega} \sum_{i=1}^d \sum_{j=1}^d \frac{1}{4} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) dx \end{aligned}$$

- FFC implementation:

```
v = BasisFunction(element)
```

```
u = BasisFunction(element)
```

```
a = 0.25 * (u[i].dx(j) + u[j].dx(i)) * \
          (v[i].dx(j) + v[j].dx(i)) * dx
```

Future directions for **FEniCS**

- New parallel mesh component (05)
- Completely parallel assembly/solve (05)
- Implementation of non-standard elements (05/06):
Crouzeix–Raviart, Raviart–Thomas, Nedelec, Brezzi–Douglas–Marini, Brezzi–Douglas–Fortin–Marini, Arnold–Winther, Taylor–Hood, ...
- Automatic generation of dual problems (06)
- Automatic generation of error estimates (06)
- Manuals, tutorials, mini-courses (05/06)
- Further information:

<http://www.fenics.org/>