

FEniCS Course

Lecture 10: Optimal control of the Navier-Stokes equations

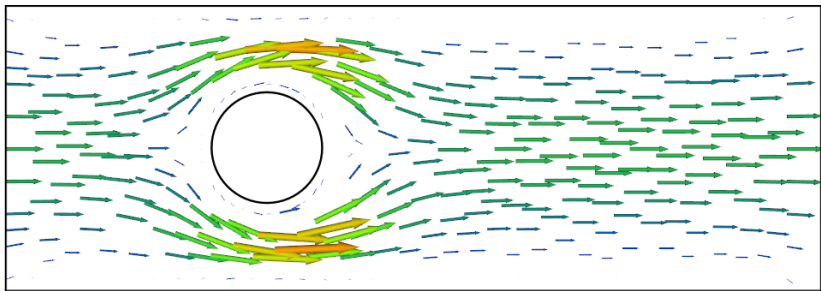
Contributors
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FENICS
PROJECT

The FEniCS challenge!

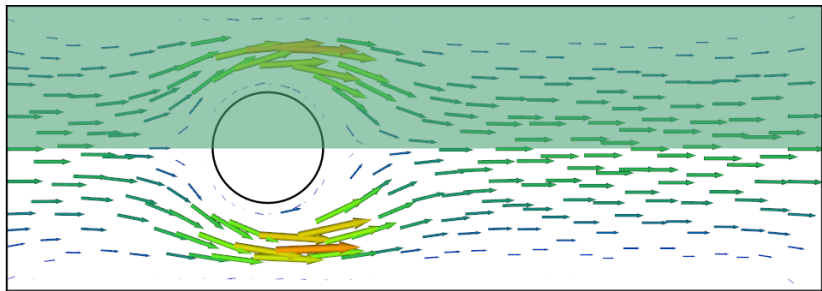
Consider flow around a cylinder driven by a pressure difference at the left and right boundaries:



- Imagine you can place sponges in the top half (light green) area of the domain.
- How would you place the sponges in order to minimise dissipation of the flow into heat?

The FEniCS challenge!

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$$\min_{u,f} \int_{\Omega} \langle \nabla u, \nabla u \rangle \, dx + \alpha \int_{\Omega} \langle f, f \rangle \, dx$$

subject to:

$$\begin{aligned} -\nu \Delta u + u \cdot \nabla u + \nabla p &= -fu && \text{in } \Omega, \\ \operatorname{div}(u) &= 0 && \text{in } \Omega, \end{aligned}$$

with:

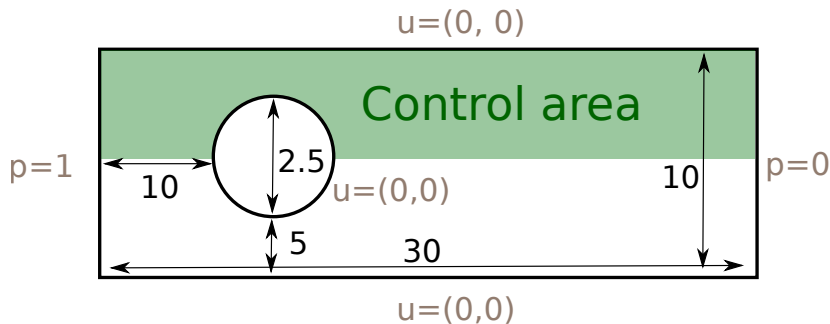
- u the velocity,
- p the pressure,
- f the control function.
- ν the viscosity,
- α the regularisation parameter,

The boundary conditions are:

- $p = 1$ on the left,
- $p = 0$ on the right,
- $u = (0, 0)$ on the top and bottom and circle.

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Domain



- 1 Write a new program and generate a mesh with the above domain.

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Navier-Stokes solver

The variational formulation of the Navier-Stokes equations is:
Find $u, p \in V \times Q$ such that:

$$\int_{\Omega} \nu \nabla u \cdot \nabla v + (u \cdot \nabla u + \nabla p + f u) \cdot v \, dx = 0 \quad \forall v \in V,$$

$$\int_{\Omega} \operatorname{div}(u) q \, dx = 0 \quad \forall q \in Q.$$

- ② Create a MixedFunctionSpace consisting of a CG_2 vector space for velocity and a CG_1 space for pressure.
- ③ Solve the Navier-Stokes equation for $f = 0$ and the given boundary conditions.

The FEniCS challenge!

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- ❷ Create a `MixedFunctionSpace` consisting of a CG_2 vector space for velocity and a CG_1 space for pressure.
- ❸ Solve the Navier-Stokes equation for $f = 0$ and the given boundary conditions.

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Optimise

- 3 Import *dolfin-adjoint* and define the parameter and functional.
- 4 Minimise the functional and plot the optimal control.
- 5 What is the minimised functional?

Note

Multiply the $\int_{\Omega} f u \cdot v \, dx$ term in the variational formulation with the indicator function:

```
chi = conditional(triangle.x[1] >= 5, 1, 0)
```

to ensure that the control is only active in the top half of the domain.