

Mechanical modelling with FEniCS

A wish list

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Interests

Example applications of FEniCS components

Wish list

Issues

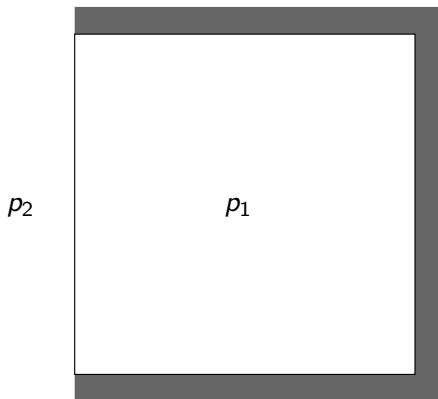
- ▶ Rapid development and efficient solution of mechanical models.
- ▶ Minimal simplicity versus computational speed compromise.
- ▶ Significant productivity increase.
- ▶ Open source.

Licensing: GPL or LGPL?

- ▶ GPL/LGPL protects *me* from my project sponsors.
- ▶ GPL might be too strong for some project sponsors.

- ▶ Nonlinear.
- ▶ Multiple fields.

Classical Biot theory + Darcy flow



Mechanical swelling due to fluid penetration

```
PU = FiniteElement("Vector Lagrange", "triangle", 2)
PP = FiniteElement("Lagrange", "triangle", 1)

ME = PU + PP

(v, q) = BasisFunctions(ME) # test functions
(u, p) = BasisFunctions(ME) # trial functions
.
.
# Bilinear and linear form for solid component
aSolid = dt*theta*dot(grad(v), stress(symgrad(u), p, mu, . . .

LSolidInt = dt*theta*dot(grad(v), stress(symgrad(u0), p0, mu, . . .
LSolidExt = dt*theta*v[1]*(rho*g)*dx

# Bilinear and linear form for fluid component
aFluid = q*comp*p*dx + q*alpha*Sw*div(u)*dx + . . .

LFluidInt = dt*theta*q*comp*pr*dx + dt*theta*q*alpha*Sw* . . .
LFluidExt = dt*theta*q*f*dx + dt*theta*perm*rhow*q.dx(1)*g*dx
```

Mechanical response

$$\nabla \cdot \boldsymbol{\sigma} + \mathbf{f} = \mathbf{0}$$

$$\boldsymbol{\sigma} = \mathcal{C} : \nabla^s \mathbf{u} - \beta \mathbf{I} c$$
$$+ B.C.$$

Steady-state diffusion

$$\nabla \cdot \mathbf{q} = 0$$

$$\mathbf{q} = -\kappa \nabla c + M \nabla (\nabla \cdot \mathbf{u})$$
$$+ B.C.$$

Find $\mathbf{u}^h \in V^h$, $e^h \in S^h$, $c^h \in X^h$ such that:

$$\left(\nabla \mathbf{w}^h, \mathbf{C} : \nabla^s \mathbf{u}^h \right)_\Omega - \left(\nabla \mathbf{w}^h, \beta \mathbf{l} c^h \right)_\Omega = \left(\mathbf{w}^h, \mathbf{f} \right) \quad \forall \mathbf{w}^h \in V^h,$$

$$\left(v^h, e^h \right)_\Omega - \left(v^h, \nabla \cdot \mathbf{u}^h \right)_\Omega = 0 \quad \forall v^h \in S^h,$$

$$\left(\nabla q^h, \kappa \nabla c^h \right)_\Omega - \left(\nabla v^h, M \nabla e^h \right)_\Omega = 0 \quad \forall q^h \in X^h.$$

Mechanically-driven diffusion in elastic solids

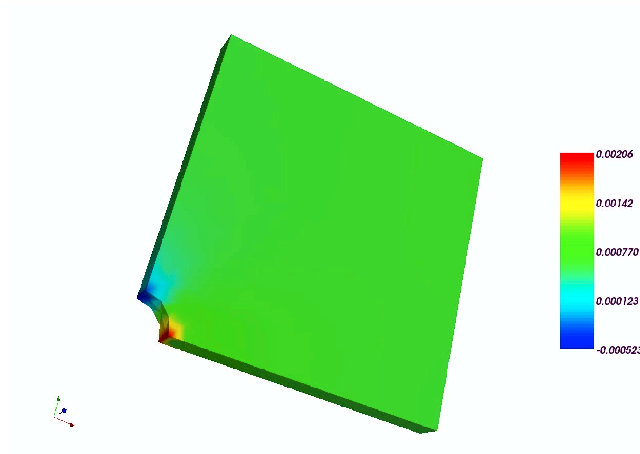
```
E1 = FiniteElement("Vector Lagrange", "tetrahedron", 2)
E2 = FiniteElement("Lagrange", "tetrahedron", 1)
E3 = FiniteElement("Lagrange", "tetrahedron", 1)

element = E1 + E2 + E3
.
.
# Elasticity
au = . . .

# Divergence of u
ae = . . .

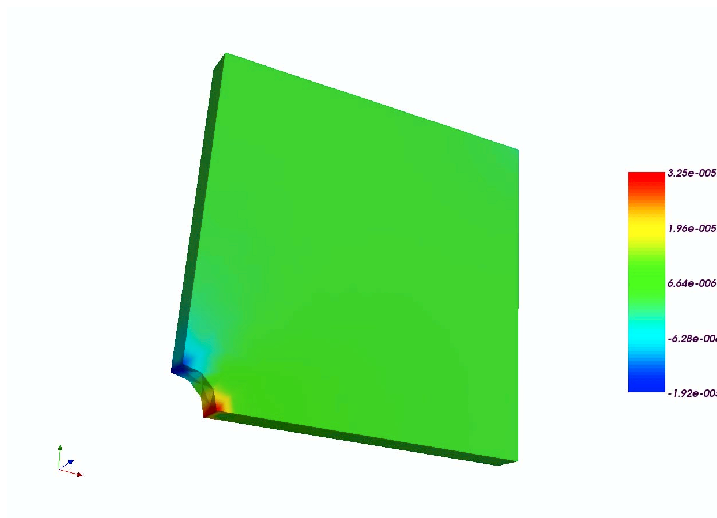
# Diffusion
ac = . . .
.
.
```

Mechanically-driven diffusion in elastic solids



dilation

Mechanically-driven diffusion in elastic solids



concentration

Model for phase separation

- ▶ Important in material science and other fields.
- ▶ Diffuse interface model.
- ▶ Fourth-order in space nonlinear parabolic equation.

$$\dot{c} = \nabla \cdot M(c) \nabla (\mu_c(c) - \lambda \nabla^2 c) \quad \text{in } \Omega$$

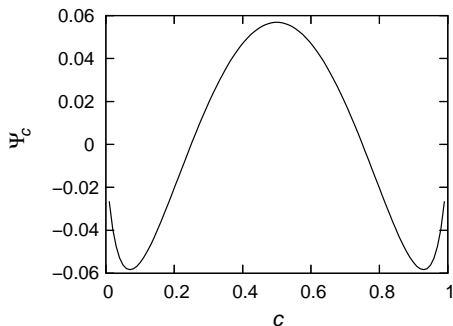
$$M \lambda \nabla c \cdot \mathbf{n} = 0 \quad \text{on } \partial\Omega$$

$$M \nabla (\mu_c - \lambda \nabla^2 c) \cdot \mathbf{n} = 0 \quad \text{on } \partial\Omega$$

- ▶ c : concentration $0 < c < 1$
- ▶ M : mobility
- ▶ μ_c : chemical potential ($= d\Psi_c/dc$)
- ▶ λ : surface energy term

Cahn-Hilliard equation

Chemical free-energy ψ^c



Surface free-energy ψ^s

$$\psi^s = \frac{1}{2} \lambda \nabla c : \nabla c$$

Mixed formulation:

$$\dot{c} = \nabla \cdot (M \nabla (\mu_c - \kappa)),$$

$$\kappa = \lambda \nabla^2 c.$$

Find $c^h \in S^h \times [0, T]$ and $\kappa^h \in P^h$ such that

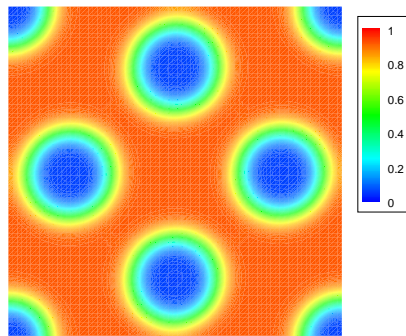
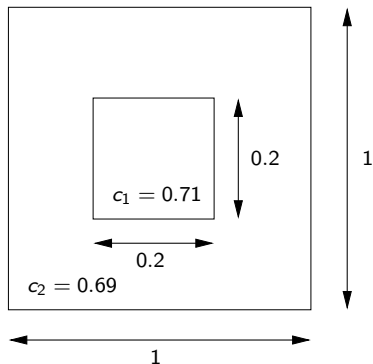
$$\left(w^h, \dot{c}^h \right)_\Omega + \left(\nabla w^h, M^h \nabla (\mu_c^h - \kappa^h) \right)_\Omega = 0 \quad \forall w^h \in V^h,$$

$$\left(v^h, \kappa^h \right)_\Omega + \left(\nabla v^h, \lambda \nabla c^h \right)_\Omega = 0 \quad \forall v^h \in Q^h,$$

$$\left(w^h, c(\mathbf{x}, 0) \right)_\Omega = \left(w^h, c_0(\mathbf{x}) \right)_\Omega \quad \forall w^h \in V^h.$$

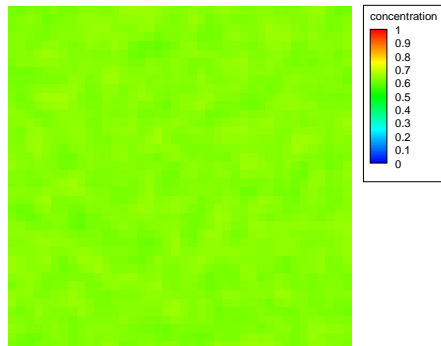
Cahn-Hilliard equation

Benchmark



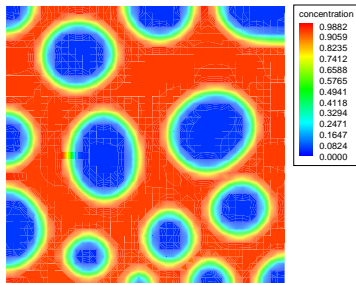
Cahn-Hilliard equation

Randomly perturbed initial conditions.

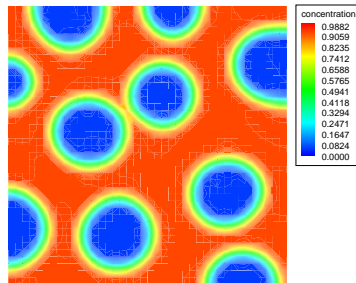


Initial condition $c = 0.63 +$ small random fluctuation.

Cahn-Hilliard equation

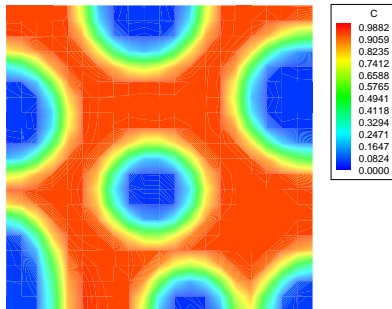


low surface energy



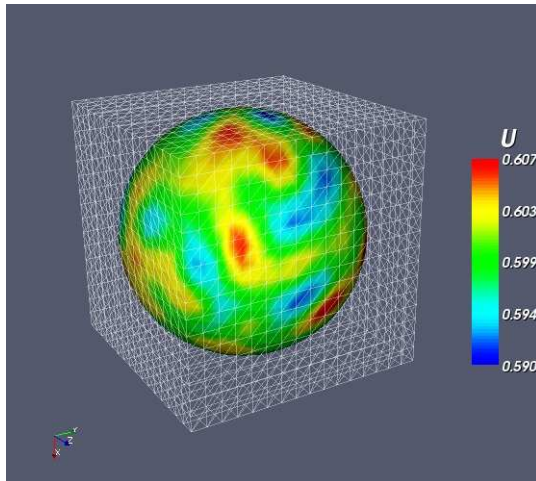
higher surface energy

Cahn-Hilliard equation



. . . even higher surface energy

Cahn-Hilliard equation



3D plane

DOLFIN

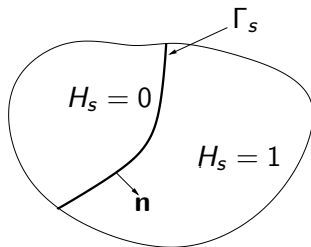
Problem: cannot find an iterative solver that works.

Find $c^h \in \mathcal{V}^h \times [0, T]$ such that

$$\begin{aligned} & \left(w^h, \dot{c}^h \right)_{\Omega} + \left(\nabla w^h, M^h \nabla \mu_c^h \right)_{\Omega} + \left(\nabla^2 w^h, M^h \lambda \nabla^2 c^h \right)_{\tilde{\Omega}} \\ & + \left(\nabla w^h, \nabla M^h \lambda \nabla^2 c^h \right)_{\tilde{\Omega}} - \left(\llbracket \nabla w^h \rrbracket, \langle M^h \lambda \nabla^2 c^h \rangle \right)_{\tilde{\Gamma}} \\ & - \left(\langle M^h \lambda \nabla^2 w^h \rangle, \llbracket \nabla c^h \rrbracket \right)_{\tilde{\Gamma}} - \left(\nabla w^h \cdot \mathbf{n}, M^h \lambda \nabla^2 c^h \right)_{\Gamma} \\ & - \left(M^h \lambda \nabla^2 w^h, \nabla c^h \cdot \mathbf{n} \right)_{\Gamma} + \left(\beta \nabla w^h \cdot \mathbf{n}, \nabla c^h \cdot \mathbf{n} \right)_{\Gamma} \\ & + \left(\beta \llbracket \nabla w^h \rrbracket, \llbracket \nabla c^h \rrbracket \right)_{\tilde{\Gamma}} = 0 \quad \forall w^h \in \mathcal{V}^h \end{aligned}$$

Approach:

$$\mathbf{u}^h = \bar{\mathbf{u}}^h + H_s \tilde{\mathbf{u}}^h$$

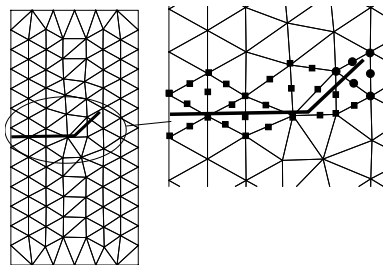


Discontinuity surface evolves.

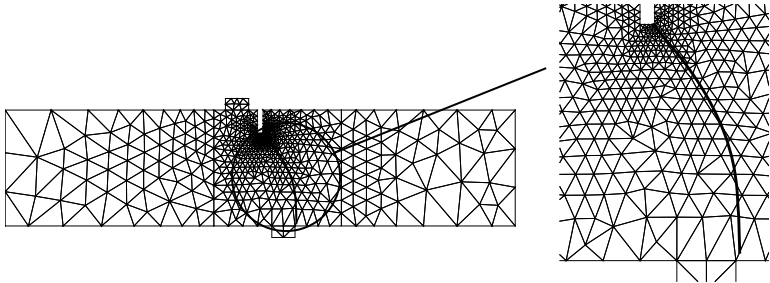
Modelling discontinuities

Exploit partition of unity property (Melenk & Babuska, Duarte & Oden, Belytschko & Black)

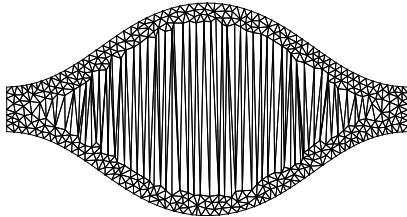
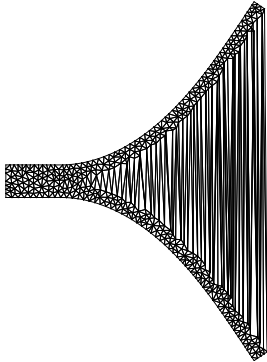
$$u^h = \sum_{i=1}^n \phi_i a_i + \sum_{j=1}^m H_s \phi_j b_j$$



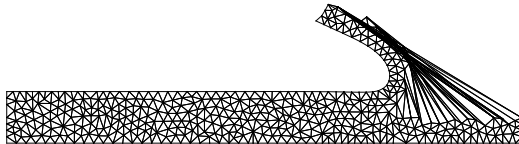
Crack propagation



Delamination



Delamination



Requirements

- ▶ Abstract evolving surface representation.
- ▶ Integration on an evolving surface.

Find . . .

$$\begin{aligned} & \left(\nabla \bar{\mathbf{w}}^h, C : \nabla^s \left(\bar{\mathbf{u}}^h + H_s \tilde{\mathbf{u}}^h \right) \right)_{\Omega} + \left(\nabla \tilde{\mathbf{w}}^h, C : \nabla^s \left(\bar{\mathbf{u}}^h + H_s \tilde{\mathbf{u}}^h \right) \right)_{\Omega^+} \\ & + \left(\tilde{\mathbf{w}}^h, \mathbf{t} \left(\tilde{\mathbf{u}}^h \right) \right)_{\Gamma_s} = \left(\mathbf{w}^h, \mathbf{f} \right)_{\Omega} \quad \forall \bar{\mathbf{w}}^h \in \bar{V}^h, \tilde{\mathbf{w}}^h \in \tilde{V}^h \end{aligned}$$

General wishes (FFC)

- ▶ Complex numbers.
- ▶ Inter-element boundary integrals.
- ▶ Simple polar coordinates.

- ▶ Variational problem compact.
- ▶ Linearised and time-dependent form very large (decrease in readability).

- ▶ Students
 - ▶ Loss of transparency.
 - ▶ Don't develop skills to implement models going beyond the current capabilities of FIAT/FFC/DOLFIN.
- ▶ Penetration
 - ▶ Level of abstraction too high for old-style FE users.
 - ▶ Quadrilateral and brick elements.
- ▶ Developers ready for users?
 - ▶ Preparedness/time to help novice users with trivial questions?
 - ▶ 0800-Anders-and-JohanJansson-help-desk (24 hour).

Most important aspect for dragging people over the threshold:
simple, accessible demos with immediate postprocessing.

Solver demos to key mechanical problems:

- ▶ **Linear-elasticity.**
- ▶ **Classical plasticity.**
- ▶ Advection-diffusion.
- ▶ Stokes flow / incompressible elasticity.
- ▶ Incompressible Navier-Stokes.

'Extras' section outside of DOLFIN src tree.

- ▶ Bloat in number of required components.
- ▶ Version dependencies becoming an issue.
- ▶ Bundle components?

Details

- ▶ Sufficient financial structure to make contributions possible.

How to spend it?

- ▶ Meetings
- ▶ Hardware, network
- ▶ ???