FEniCS Course

Lecture 9: Incompressible Navier–Stokes

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The incompressible Navier–Stokes equations

$$\begin{split} \rho(\dot{u} + u \cdot \nabla u) - \nabla \cdot \sigma(u, p) &= f &\quad \text{in } \Omega \times (0, T] \\ \nabla \cdot u &= 0 &\quad \text{in } \Omega \times (0, T] \\ u &= g_{\text{D}} &\quad \text{on } \Gamma_{\text{D}} \times (0, T] \\ \sigma \cdot n &= g_{\text{N}} &\quad \text{on } \Gamma_{\text{N}} \times (0, T] \\ u(\cdot, 0) &= u_0 &\quad \text{in } \Omega \end{split}$$

- \bullet u is the fluid velocity and p is the pressure
- ρ is the fluid density
- $\sigma(u,p) = 2\mu\epsilon(u) pI$ is the Cauchy stress tensor
- $\epsilon(u) = \frac{1}{2}(\nabla u + \nabla u^{\top})$ is the strain rate tensor
- f is a given body force per unit volume
- $g_{\rm D}$ is a given boundary velocity
- $g_{\rm N}$ is a given boundary traction
- u_0 is a given initial velocity

Mixed variational formulation of Navier-Stokes

Multiply the momentum equation by a test function v and integrate by parts:

$$\int_{\Omega} \rho(\dot{u} + u \cdot \nabla u) \cdot v \, \mathrm{d}x + \int_{\Omega} \sigma(u, p) : \epsilon(v) \, \mathrm{d}x = \int_{\Omega} f \cdot v \, \mathrm{d}x + \int_{\Gamma_{\mathrm{N}}} g_{\mathrm{N}} \cdot v \, \mathrm{d}s$$

Short-hand notation: $\langle \cdot, \cdot \rangle$ is L^2 -inner product

$$\langle \rho \dot{u}, v \rangle + \langle \rho u \cdot \nabla u, v \rangle + \langle \sigma(u, p), \epsilon(v) \rangle = \langle f, v \rangle + \langle g_{\rm N}, v \rangle_{\Gamma_{\rm N}}$$

Multiply the continuity equation by a test function q and sum up: find $(u, p) \in V$ such that

$$\langle \rho \dot{u}, v \rangle + \langle \rho u \cdot \nabla u, v \rangle + \langle \sigma(u, p), \epsilon(v) \rangle + \langle \nabla \cdot u, q \rangle = \langle f, v \rangle + \langle g_{\rm N}, v \rangle_{\Gamma_{\rm N}}$$

for all
$$(v,q) \in \hat{V}$$

Discrete mixed variational form of Navier-Stokes

Time-discretization leads to a *saddle-point* problem on each time step:

$$\begin{bmatrix} M + \Delta t A + \Delta t N(U) & \Delta t B \\ \Delta t B^{\top} & 0 \end{bmatrix} \begin{bmatrix} U \\ P \end{bmatrix} = \begin{bmatrix} b \\ 0 \end{bmatrix}$$

- Efficient solution of the saddle-point problem relies on the efficiency of special-purpose preconditioners (Uzawa iteration, Schur complement preconditioners, ...)
- We will use another approach (simpler and often more efficient)

A spliting scheme for Navier-Stokes

Use a Crank-Nicolson approximation with explicit convention for the time-discretization of the momentum equation:

$$\rho D_t u^n + \rho u^{n-1} \cdot \nabla u^{n-1} - \nabla \cdot \sigma(u^{n-1/2}, p^{n-1/2}) = f^{n-1/2}$$

Step 1: Compute the *tentative velocity* u^* using the approximation

$$\rho D_t u^{\bigstar} + \rho u^{n-1} \cdot \nabla u^{n-1} - \nabla \cdot \sigma(u^{n-1/2}, \mathbf{p}^{n-3/2}) = f^{n-1/2}$$

$$D_t u = (u^n - u^{n-1})/k_n$$
 and $k_n = t_n - t_{n-1}$

A splitting scheme for N-S (contd.)

Subtract the equation for the tentative velocity from the equation for the *real* velocity:

$$\rho(D_t u^n - D_t u^*) - \nabla \cdot \sigma(0, p^{n-1/2} - p^{n-3/2}) = 0$$

Expanding the D_t , using the equations, and rearranging give

$$\rho u^n = \rho u^* - k_n \nabla (p^{n-1/2} - p^{n-3/2}) \tag{1}$$

Take the divergence and set $\nabla \cdot u^n = 0$:

$$-k_n \Delta p^{n-1/2} = -k_n \Delta p^{n-3/2} - \rho \nabla \cdot u^{\bigstar} \tag{2}$$

- Step 2: Compute $p^{n-1/2}$ by solving the Poisson problem (2)
- Step 3: Compute u^n by solving the projection problem (1)

NB: Which boundary conditions for the Poisson problem (2)?

Boundary conditions

• For outflow boundary conditions, corresponding to so-called "do-nothing" boundary conditions for the Laplacian formulation, we take $\partial_n u = 0$:

$$\sigma(u, p) \cdot n = (2\mu\epsilon(u) - pI) \cdot n = \mu \nabla u \cdot n + \mu(\nabla u)^{\top} \cdot n - pn$$
$$= \mu \nabla u \cdot n - pn \approx \mu \nabla u^{n-1/2} \cdot n - p^{n-3/2}n$$

• Boundary conditions for the pressure Poisson problem:

$$\partial_n \dot{p} = 0$$

on the pressure Neumann boundary

Incremental pressure correction scheme (IPCS)

1 Compute the tentative velocity u^* by

$$\langle \rho D_t^n u^{\bigstar}, v \rangle + \langle \rho u^{n-1} \cdot \nabla u^{n-1}, v \rangle + \langle \sigma(u^{n-\frac{1}{2}}, p^{n-3/2}), \epsilon(v) \rangle$$
$$- \langle \mu \nabla u^{n-\frac{1}{2}} \cdot n, v \rangle_{\partial \Omega} + \langle p^{n-3/2} n, v \rangle_{\partial \Omega} = \langle f^{n-1/2}, v \rangle$$

2 Compute the corrected pressure $p^{n-1/2}$ by

$$k_n \langle \nabla p^{n-1/2}, \nabla q \rangle = k_n \langle \nabla p^{n-3/2}, \nabla q \rangle - \langle \rho \nabla \cdot u^{\bigstar}, q \rangle$$

3 Compute the corrected velocity u^n by

$$\langle \rho u^n, v \rangle = \langle \rho u^{\bigstar}, v \rangle - k_n \langle \nabla (p^{n-1/2} - p^{n-3/2}), v \rangle$$

Useful FEniCS tools (I)

```
Note grad vs. \nabla:

Python code

dot(grad(u), u)

dot(u, nabla_grad(u))
```

Defining operators: $Python\ code$

```
def sigma(u, p):
    return 2.0*mu*sym(grad(u))-p*Identity(len(u))
```

The facet normal n: $Python\ code$

```
n = FacetNormal(mesh)
```

Useful FEniCS tools (II)

Assembling matrices and vectors: $\begin{cal}P\end{color}$ $\begin{cal}P\end{color}$

```
A = assemble(a)
b = assemble(L)
```

Solving linear systems:

 $Python\ code$

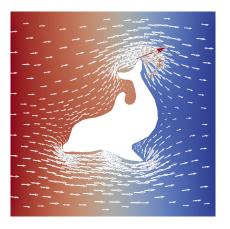
```
solve(A, x, b)
solve(A, x, b, "gmres", "ilu")
solve(A, x, b, "cg", "amg")
```

Extracting left- and right-hand sides: $\begin{cal}P\end{code}$

```
F = <complicated expression>
a = lhs(F)
L = rhs(F)
```

The FEniCS challenge!

Solve the incompressible Navier–Stokes equations for the flow of water around a dolphin. The water is initially at rest and the flow is driven by a pressure gradient.



The FEniCS challenge!

- Use the mesh dolfin_channel.xml.gz.
- Compute the solution on the time interval [0, 0.1] with time steps of size k = 0.0005
- Set p = 1 kPa at the inflow and p = 0 at the outflow
- The density of water is $\rho = 1000 \text{ kg/m}^3$ and the viscosity is $\mu = 0.001002 \text{ kg/(m} \cdot \text{s})$
- To check your answer, compute the average velocity in the *x*-direction:

$$\bar{u}_x = \frac{1}{|\Omega|} \int_{\Omega} u \cdot (1,0) \, \mathrm{d}x$$

The student(s) who first produce the right answer will be rewarded with an exclusive FEniCS surprise!